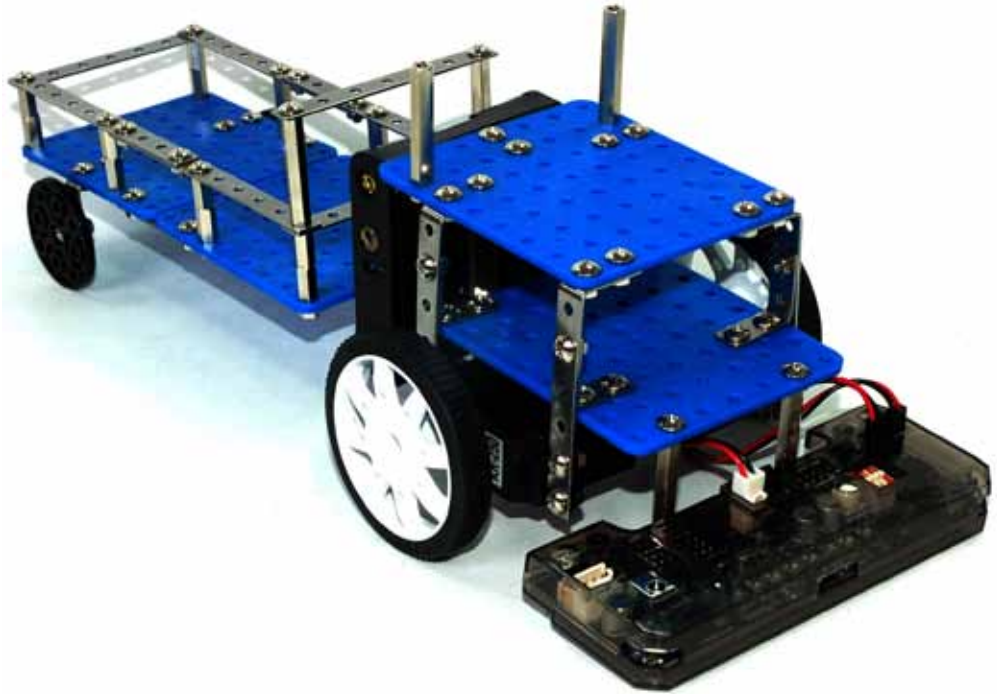


## 6. 트레일러 로봇 (Trailer Robot)



# 소개 및 동작원리

– Introduction & working principle



리모컨으로 조종할 수 있는 조종형 로봇으로서 짐을 실을 수 있는 트레일러가 달려 있습니다. 로봇 본체와 트레일러는 실제 트럭처럼 굴절 구조로 되어 있어 트럭이 좌우로 움직일 때에도 본체와 트레일러가 서로 최대한 움직임을 구속하지 않고 유연하게 동작합니다.



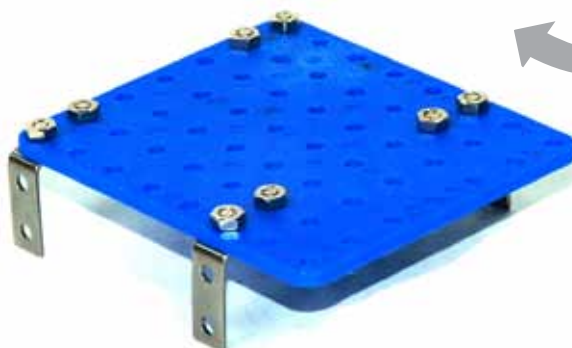
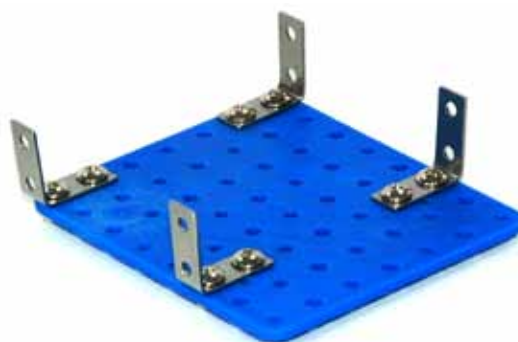
1



X 8



X 8



2



X 10



X 10



3

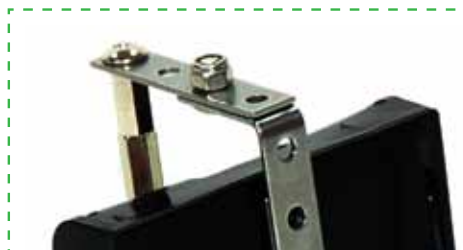


X 2 X 2

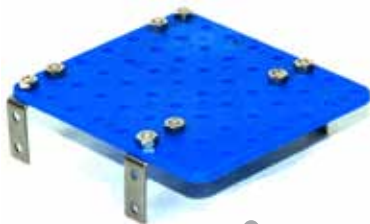
4



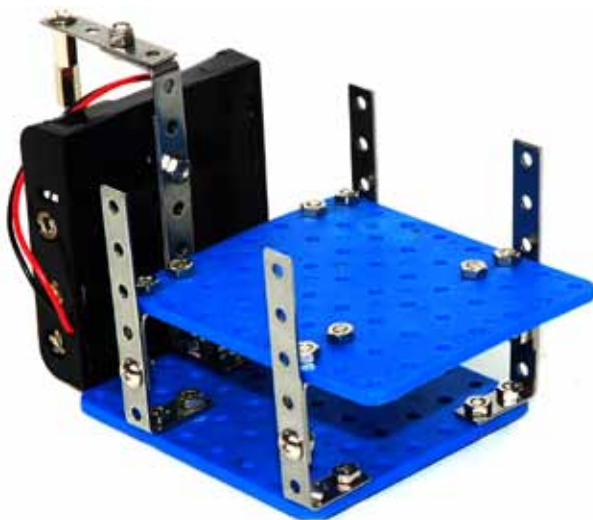
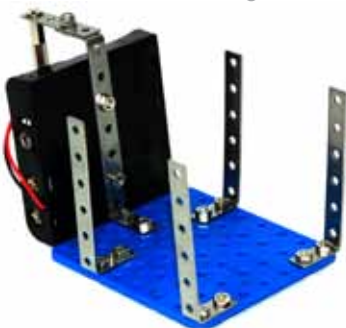
X 2 X 1



5



+



X 4



X 4

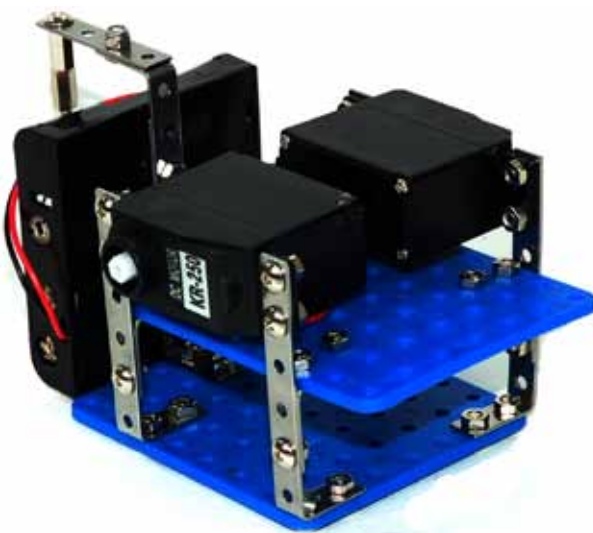
6



X 8



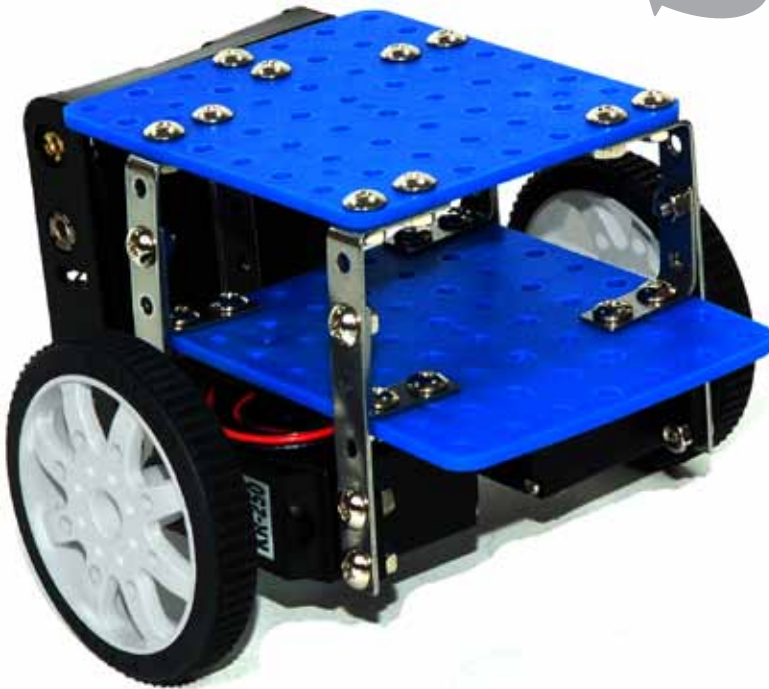
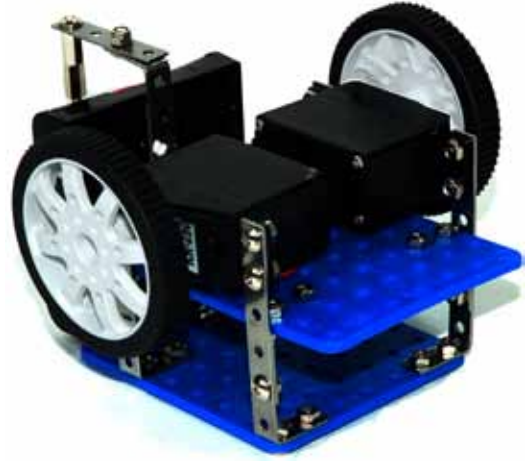
X 8



7



X 2



8

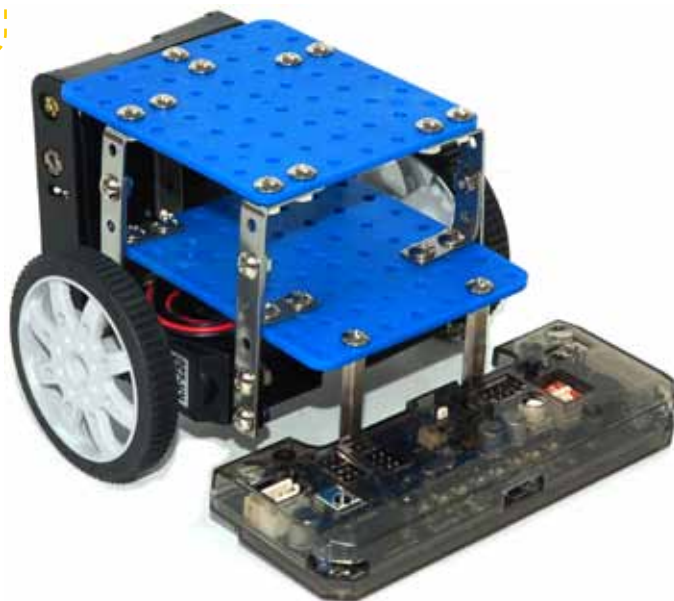


X 2

9



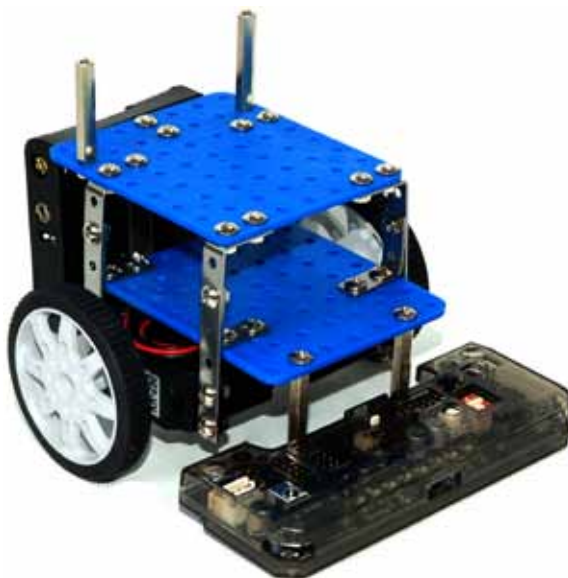
X 2



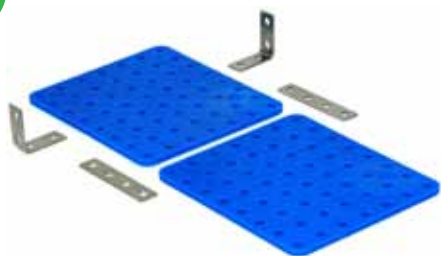
10



X 2



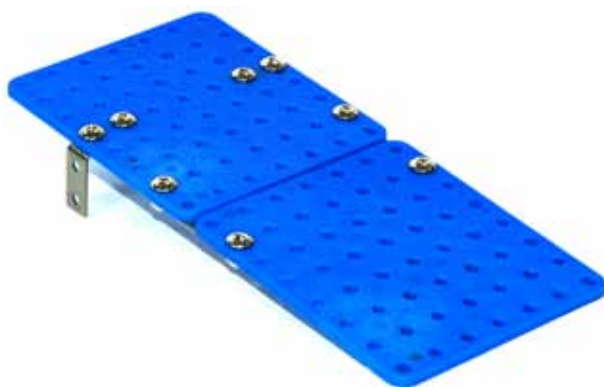
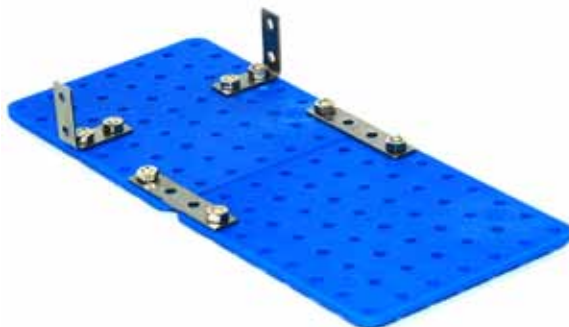
11



X 8



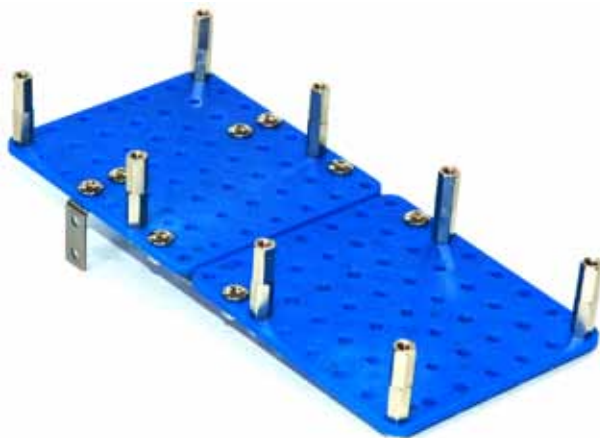
X 8



12



X 8



13



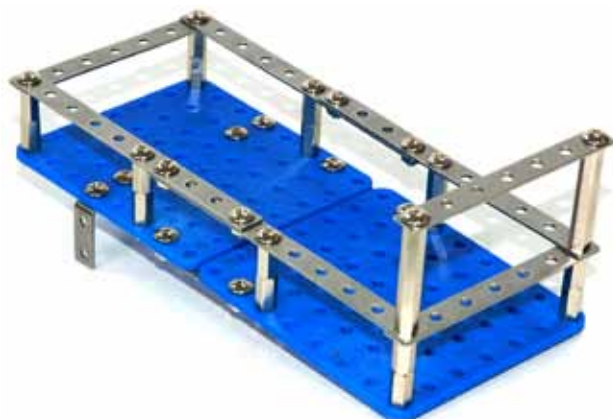
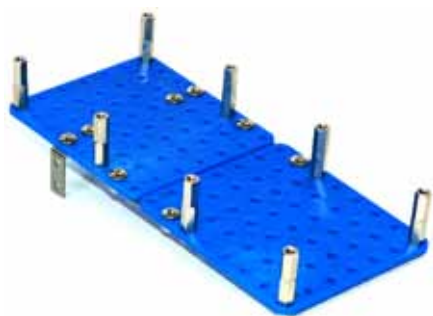
X 4



X 4



14



X 8

15

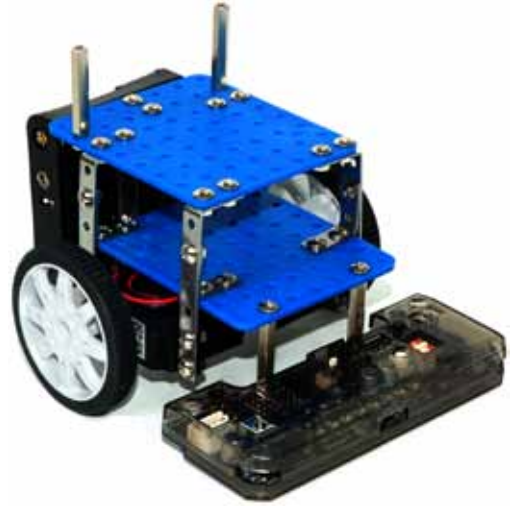


X 2

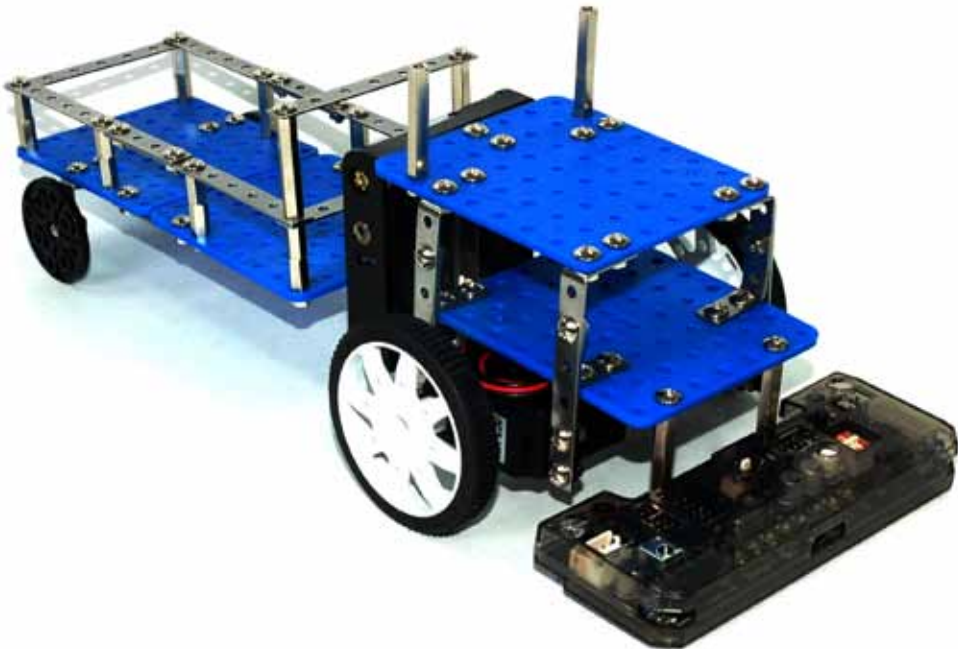


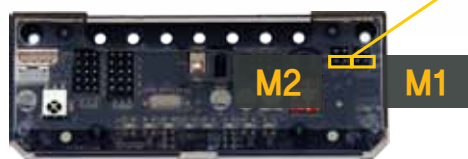
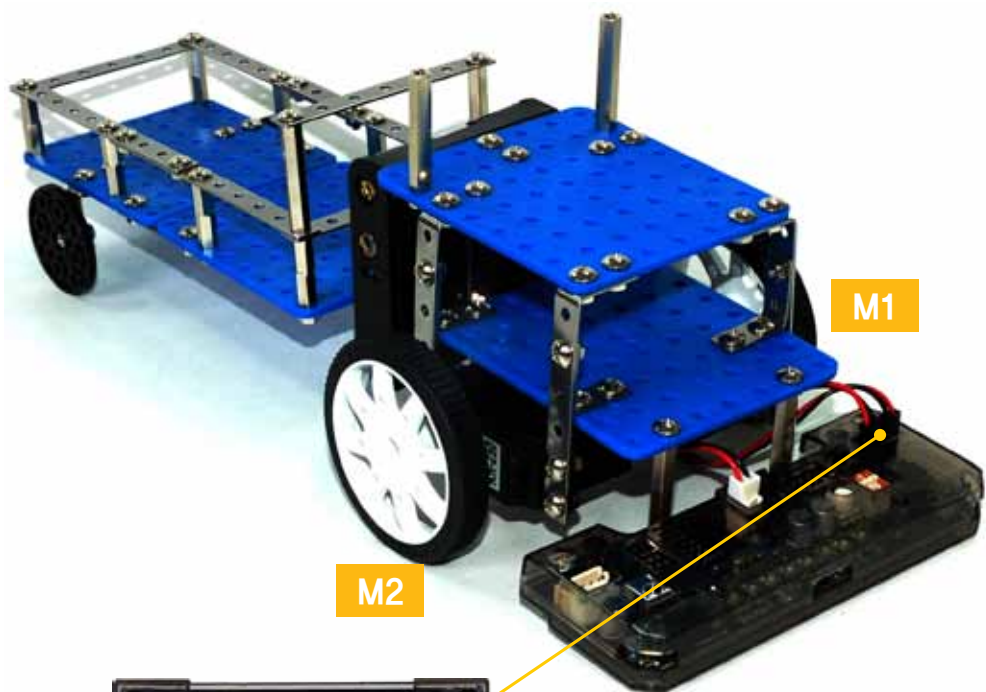
X 2

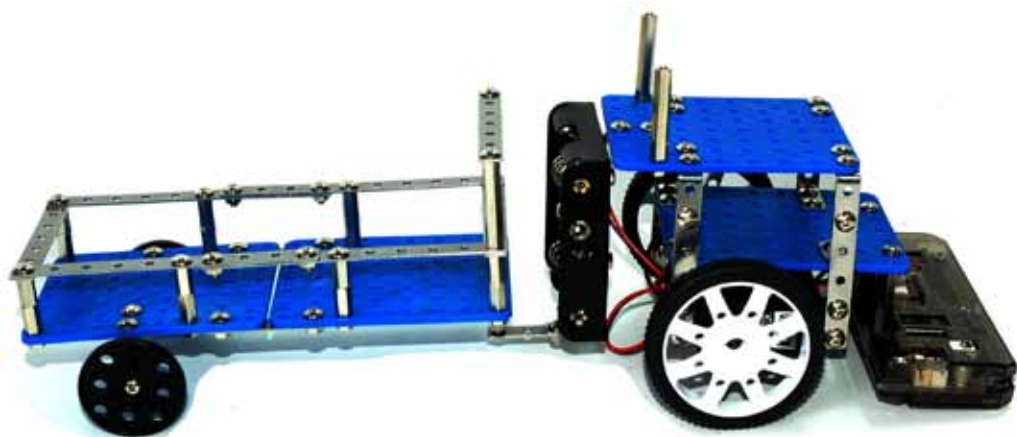
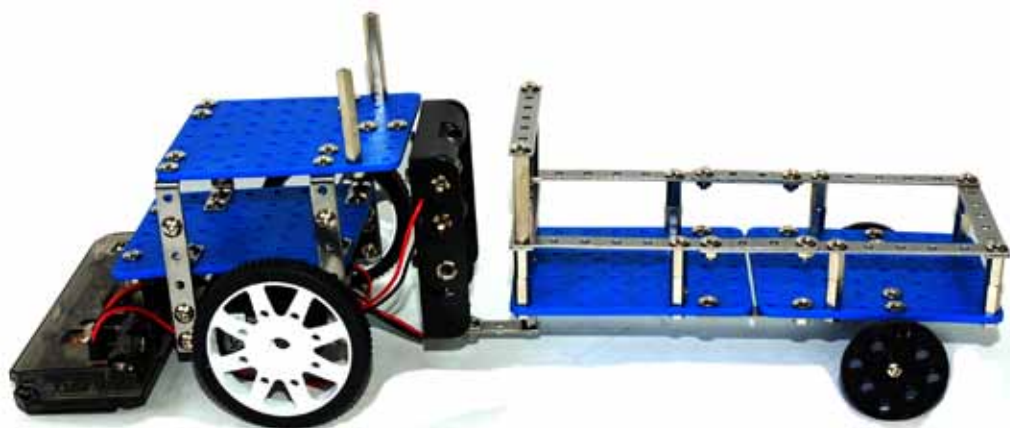




X 1



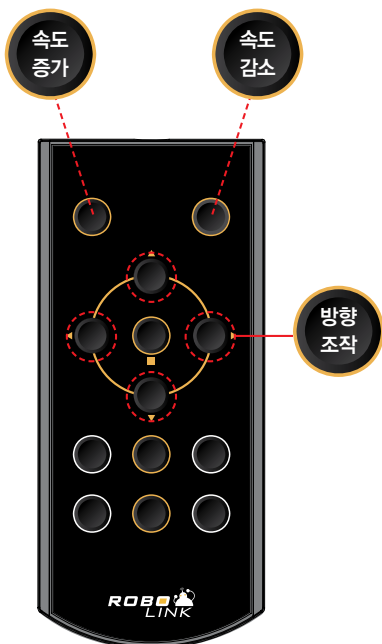
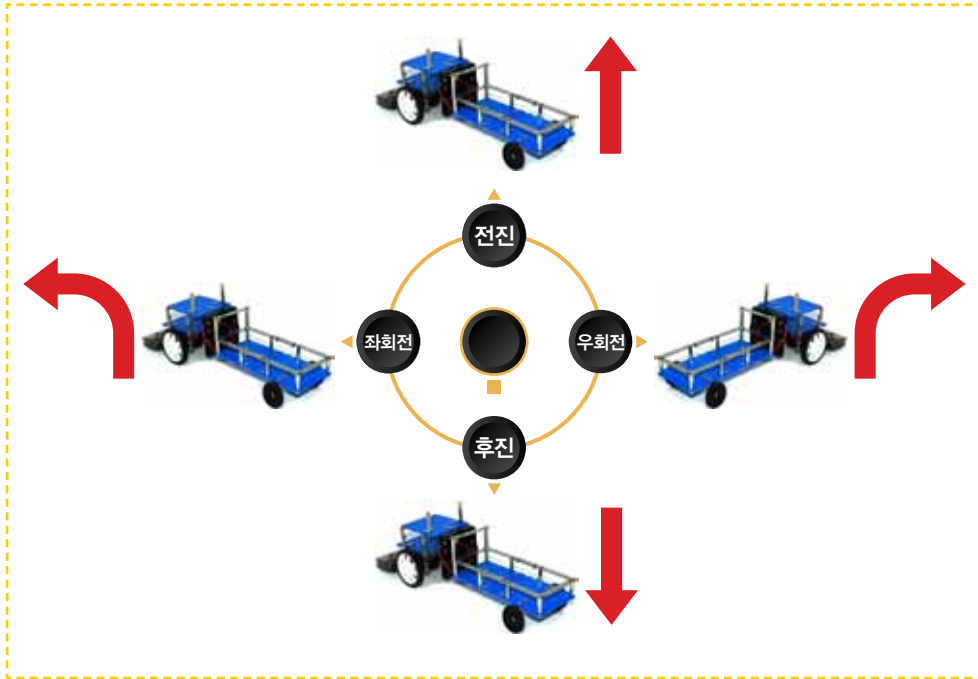




# 구동하기



트레일러 로봇은 프로그램 모드 6번을 선택하여 구동합니다.



속도가 증가할수록, 불빛이 증가합니다.



← 속도가 낮을 때 →



← 속도가 높을 때 →